

◎ Gauss-Jordan Elimination

Given A , we want to find its inverse A^{-1} .

$$AA^{-1} = I$$

$$A \begin{bmatrix} \underline{x_1} & \underline{x_2} & \underline{x_3} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \underline{e_1} & \underline{e_2} & \underline{e_3} \end{bmatrix}$$

$$\begin{array}{l} \text{Gauss} \\ \downarrow \\ \left[\begin{array}{ccc|ccc} \textcircled{2} & -1 & 0 & 1 & 0 & 0 \\ -1 & 2 & -1 & 0 & 1 & 0 \\ 0 & -1 & 2 & 0 & 0 & 1 \end{array} \right] \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 2 & -1 & 0 & 1 & 0 & 0 \\ 0 & \textcircled{\frac{3}{2}} & -1 & \frac{1}{2} & 1 & 0 \\ 0 & -1 & 2 & 0 & 0 & 1 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 2 & -1 & 0 & 1 & 0 & 0 \\ 0 & \frac{3}{2} & -1 & \frac{1}{2} & 1 & 0 \\ 0 & 0 & \textcircled{\frac{4}{3}} & \frac{1}{3} & \frac{2}{3} & 1 \end{array} \right]$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 2 & -1 & 0 & 1 & 0 & 0 \\ 0 & \frac{3}{2} & 0 & \frac{2}{3} & \frac{2}{3} & \frac{3}{4} \\ 0 & 0 & \textcircled{\frac{4}{3}} & \frac{1}{3} & \frac{2}{3} & 1 \end{array} \right]$$

$$\begin{array}{l} \text{Jordan} \\ \downarrow \\ \Rightarrow \left[\begin{array}{ccc|ccc} 2 & 0 & 0 & \frac{3}{2} & 1 & \frac{1}{2} \\ 0 & \textcircled{\frac{3}{2}} & 0 & \frac{3}{4} & \frac{2}{3} & \frac{3}{4} \\ 0 & 0 & \frac{4}{3} & \frac{1}{3} & \frac{2}{3} & 1 \end{array} \right] \end{array}$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{3}{4} & \frac{1}{2} & \frac{1}{4} \\ 0 & 1 & 0 & \frac{1}{2} & 1 & \frac{1}{2} \\ 0 & 0 & 1 & \frac{1}{4} & \frac{1}{2} & \frac{3}{4} \end{array} \right]$$

$$\therefore \underline{x_1} = \begin{bmatrix} \frac{3}{4} \\ \frac{1}{2} \\ \frac{1}{4} \end{bmatrix} \quad \underline{x_2} = \begin{bmatrix} \frac{1}{2} \\ 1 \\ \frac{1}{2} \end{bmatrix} \quad \underline{x_3} = \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ \frac{3}{4} \end{bmatrix}$$

$$\Rightarrow A^{-1} = \begin{bmatrix} \frac{3}{4} & \frac{1}{2} & \frac{1}{4} \\ \frac{1}{2} & 1 & \frac{1}{2} \\ \frac{1}{4} & \frac{1}{2} & \frac{3}{4} \end{bmatrix}$$

In another viewpoint,

$$\left[A \mid I \right] \Rightarrow \left[I \mid A^{-1} \right] \text{ by performing elementary row operations}$$

$$\text{because } A^{-1} \left[A \mid I \right] = \left[I \mid A^{-1} \right]$$

Def An $n \times n$ matrix is nonsingular if it has a full set of n (nonzero) pivots.

Claim A matrix is invertible if and only if it is nonsingular.
(iff)

Proof " \Leftarrow "

Suppose A is nonsingular, i.e., it has a full set of n pivots.
Then by Gauss-Jordan elimination, we can find a matrix B such that
 $AB = I$ (since $Ax_i = e_i$ is solvable for all $i = 1, 2, \dots, n$)

\rightarrow right inverse

On the other hand, Gauss-Jordan elimination is really a sequence of multiplications by elementary matrices on the left $(D^{-1} \dots E \dots P \dots E)A = I$

where E_{ij} : to subtract a multiple λ_{ij} of row j from row i .

P_{ij} : to exchange rows i and j .

D^{-1} : to divide all rows by their pivots.

That is, there is a matrix G such that $GA = I$

Therefore, $B = G = A^{-1}$ and A is invertible.

" \Rightarrow " If A does not have n pivots, ^(A is singular) elimination will lead to a zero row, i.e., there is an invertible M such that a row of MA is zero.
If $AG = I$ is possible, then $MA G = M$

$$(MA)G = M$$

\hookrightarrow has a zero row \rightarrow has a zero row

Hence M must have a zero row, which reaches a contradiction since M is invertible. Therefore, A is not invertible. ■

◎ Elimination = Factorization: $A = LU$

$$x-2 \hookrightarrow \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix}$$

$$\Rightarrow x1 \hookrightarrow \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ -2 & 7 & 2 \end{bmatrix}$$

$$\Rightarrow x1 \hookrightarrow \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 8 & 3 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$(E_{32} E_{31} E_{21}) A = U \rightarrow$ upper-triangular

$$\begin{bmatrix} 1 & 0 & 0 \\ -l_{21} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow E_{21}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ e_{21} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -l_{31} & 0 & 1 \end{bmatrix} E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \Rightarrow E_{31}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ l_{31} & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -l_{32} & 1 \end{bmatrix} E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \Rightarrow E_{32}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & l_{32} & 1 \end{bmatrix}$$

$(E_{32} E_{31} E_{21}) A = U$

$$\Rightarrow A = (E_{21}^{-1} E_{31}^{-1} E_{32}^{-1}) U$$

$$\begin{aligned} E_{21}^{-1} E_{31}^{-1} E_{32}^{-1} &= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & -1 & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & -1 & 1 \end{bmatrix} \end{aligned}$$

In general,

$$\begin{aligned} E_{21}^{-1} E_{31}^{-1} E_{32}^{-1} &= \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ l_{31} & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & l_{32} & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 1 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix} \end{aligned}$$

$= L$ lower-triangular

Note $E_{32} E_{31} E_{21} \neq \begin{bmatrix} 1 & 0 & 0 \\ -l_{21} & 1 & 0 \\ -l_{31} & -l_{32} & 1 \end{bmatrix}$

$\therefore A = LU$ if no row exchanges are required

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$A \qquad L \qquad U$

We can further split U into

$$\begin{bmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \textcircled{2} & 0 & 0 \\ 0 & \textcircled{-8} & 0 \\ 0 & 0 & \textcircled{1} \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & \frac{1}{4} \\ 0 & 0 & 1 \end{bmatrix}$$

pivots

$\therefore A = LDU$ if no row exchanges are required

$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & -8 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & \frac{1}{4} \\ 0 & 0 & 1 \end{bmatrix}$$

where L is a lower-triangular matrix with 1's on the diagonal.
(which records the steps of elimination)

D is a diagonal matrix with pivots on the diagonal.

U is an upper-triangular matrix with 1's on the diagonal.

Claim If $A = L_1 D_1 U_1$ and $A = L_2 D_2 U_2$, where the L 's are lower-triangular with unit diagonal, the U 's are upper-triangular with unit diagonal, and the D 's are diagonal matrices with no zeros on the diagonal, then $L_1 = L_2$, $D_1 = D_2$, $U_1 = U_2$.

Proof Exercise.